APPENDIX I

```
% Creating a network topology object

network_topo = topo('init');          % graphically place nodes on screen
addlink(network_topo);                % graphically connect up nodes
labelnames(network_topo);             % graphically label nodes

save network_topo;                    % save network_topo for future use


% Top level procedure to compute paths that optimize use of network capacity
% inputs:
%       D = traffic demand matrix
%         (retrieved from predictions stored in TMS Statistics Repository)
%       network_topo = topology object defining the network topology
%       P = network policy information
%          (matrix of reserved capacity, which indicates links whose use
%           is administratively prohibited or which should not be
%            completely allocated)
% outputs:
%       allocated_paths() = list of paths to set up, to TMS signalling system


C = capacity(network_topo);           % retrieve network topology information
C = C - P;

saved_C = [];
saved_SLA = [];
assigned_paths = [];
round = 0;

[SLA, S] = create_ordered_sla(D);

F = SLA(1)

for F = SLA',
        round = round +1;
        saved_C{round} = C;
        saved_SLA{round} = F;

        F % display the flow

        W = calc_weights('calcweight2',F,C);
        [dist, P] = floyd(W);
```

```
            path = findpath(P,F.i,F.j);

            assigned_paths{round}.path = path;
            assigned_paths{round}.flow = F;

            if (isempty(path))
                    fprintf(1,'no path for flow:\n'); F
            else
                    C = compute_residual_capacity('c - F.bw',path,F,C);
            end

    end

    function [W] = calc_weights(func,F,C)
    % function [W] = calc_weights(func,F,C)
    %
    %  Compute the weights by calling func on each elt of C
    %  func must be of the form double func(Flow F, Capacity_elt c, node i, node j)

    func = fcnchk(func);

    for i = 1:size(C,1)
            for j = 1:size(C,2)
                    W(i,j) = feval(func,F,C(i,j),i,j);
            end
    end

    function [w] = calcweight2(F,c,i,j)
    % function [w] = calcweight2(F,c,i,j)
    %   basic weight calc

    if (0 == c)
            w = inf;
            return;
    end


    % rule out paths that can't hack it
    if (F.bw > c)
            w = inf;
            return;
    end
```

```
w = 1 / (c - F.bw) ;  % fill links with most capacity first

function [C] = compute_residual_capacity(func, path, F, C)
% function [C] = compute_residual_capacity(func, path, F, C)
%
%  Update capacity characteristics in C to reflect flow F being
%  allocated along path using function func
%    func should be of the form
%       C_element func(C_element c, Flow F)


if (length(path) <= 1)
        return;
end

func = fcnchk(func,'c','F');

index = 1;
src = path(index);
index = index + 1;

for index = index:length(path)
        dst = path(index);

        C(src,dst) = feval(func,C(src,dst),F);

        src = dst;
end

function [SLA, S] = create_ordered_sla(D)
% function [SLA] = create_ordered_sla(D)
% takes the demand matrix and returns a list of SLAs,
%      SLA of the form [ struct ; struct ; ... ] where struct is [BW, i, j]
%      S of the form [ [BW, i, j] ; [BW, i, j] ; ...]


S = [];

for i = 1:size(D,1)
        for j = 1:size(D,2)
                if (D(i,j) ~= 0)
                        S = [[D(i,j) i j ] ; S];
                end
        end
end
```

```
[Y, I] = sortrows(S,1);

S = Y(size(Y,1):-1:1,:);  % reverse order

SLA = struct('bw',num2cell(S(:,1)),'i',num2cell(S(:,2)),'j',num2cell(S(:,3)));

return;

function [path] = findpath(P,i,j)
% function [path] = findpath(P)
%
%

path = [];

if (i == j)
        path = [i];
        return;
end

if (0 == P(i,j))
        path = [];
else
        path = [findpath(P,i,P(i,j)) j];
end

function [D, P] = floyd(W)
% function [D, P] = floyd(W)
% given weights Wij, compute min dist Dij between node i to j
% on shortest path from i to j, j has immeadiate predecessor Pij

n = size(W,1);
if (n ~= size(W,2))
        error('Input W is not square??!!');
end

D = W;

P = repmat([1:n]',[1 n]);
P = P .* ~isinf(W);
P = P .* ~eye(n);

for k = 1:n
        for i = 1:n
```

```
                        for j = 1:n
                                alt_path = D(i,k) + D(k,j);
                                if (D(i,j) > alt_path)
                                        D(i,j) = alt_path;
                                        P(i,j) = P(k,j);
                                end
                        end
                end
        k;
        D;
        P;
        end
```

APPENDIX II

```
function  addlink(TOPO)
% addlink(TOPO)
%
%   interactively add links to the TOPO

update(TOPO);
c_src = 1;
c_dst = 2;
c_bw = 3;

figure(TOPO.cur_fig)

while (1)

fprintf(1,'\n\nHit Button 3 to end...\n\n');

% find coords and index i of src
[x1i y1i button] = ginput(1);
if (button == 3) break; end

d = sqrt((TOPO.locs(:,1) - x1i).^2 + (TOPO.locs(:,2) - y1i).^2);
[d,i] = min(d);
x1 = TOPO.locs(i,1); y1 = TOPO.locs(i,2);

% find coords and index j of dst
[x2i y2i] = ginput(1);
d = sqrt((TOPO.locs(:,1) - x2i).^2 + (TOPO.locs(:,2) - y2i).^2);
[d,j] = min(d);
x2 = TOPO.locs(j,1); y2 = TOPO.locs(j,2);

hold on;
lh = line([x1 x2],[y1 y2],'color','red');

cap = input('Enter capacity (in Mbps) > ');

fprintf(1,'About to create symetric %d Mbps link from node %d to node %d\n',cap,i,j);

doit = input('Enter Y to confirm, N to reject, and B to change bandwidth (Y)> ','s');

if (isempty(doit)) doit = 'Y'; end

if (doit == 'n' | doit == 'N')
        delete(lh);
        return;
```

```
end

if (doit == 'b' | doit == 'B')
        buf = sprintf('Enter capacity from %d to %d (in Mbps) > ',i,j);
        cap_i_to_j = input(buf);

        buf = sprintf('Enter capacity from %d to %d (in Mbps) > ',j,i);
        cap_j_to_i = input(buf);
else
        cap_i_to_j = cap;
        cap_j_to_i = cap;
end

%build the link records
clear linkab linkba;

linkab.src = i;
linkab.dst = j;
linkab.bw = cap_i_to_j;
linkab.handle = lh;

linkba.src = j;
linkba.dst = i;
linkba.bw = cap_j_to_i;
linkba.handle = lh;


% now draw the actual link on the map
delete(lh);
lh = drawlink(TOPO, linkab);

% now store the link info
TOPO.links = [TOPO.links ; linkab ; linkba ];
TOPO.linkarray = [TOPO.linkarray ; [ i j cap_i_to_j] ; [ j i cap_j_to_i ]];

end % of while loop

assignin('caller',inputname(1),TOPO);



function [C, portmap] = capacity(TOPO)
% [C, portmap] = capacity(TOPO)
```

```
%  portmap maps indices of C to elts of nodes(TOPO)
%     [node  dir] where
%              node is index of elt in nodes(TOPO)
%              dir is 1 if data enters here, -1 if data leaves here

numnodes = length(TOPO.links) * 2;

C = zeros(numnodes,numnodes);

curnode = 0;
portmap = [];
for i = 1:length(TOPO.links)
        link = TOPO.links(i);
        curnode = curnode + 1;
        portmap(curnode,:) = [link.src -1];
        curnode = curnode + 1;
        portmap(curnode,:) = [link.dst 1];

        C(curnode-1,curnode) = link.bw;
end

c_node = 1;
c_dir = 2;

for i = 1:length(TOPO.nodes)
        ins = find(portmap(:,c_node) == i & portmap(:,c_dir) == 1);
        outs = find(portmap(:,c_node) == i & portmap(:,c_dir) == -1);

        for j = ins
                for k = outs
                        C(j,k) = inf;
                end
        end
end
function [a, b, c] = debug(t)

update(t);

fieldnames(t)

a = t.nodes
b = t.locs
c = t.links
function display(TOPO)
% DISPLAY a topo object
```

```
% a link is a unidirectional, so the value is probably twice what you want

fprintf('[TOPO object: %d nodes %d links]\n',...
        length(TOPO.nodes),length(TOPO.links));
function draw(TOPO)
% draw(topo)
%
%   draw the topology figure in a new window

TOPO.cur_fig = figure;
axis(TOPO.axis);
axis equal;
axis manual;
box on;
hold on;

for i = 1:length(TOPO.nodes)
        nm = plot(TOPO.nodes{i}.loc(1),TOPO.nodes{i}.loc(2),'ob');
        TOPO.nodes{i}.mark_handle = nm;
        if (isfield(TOPO.nodes{i},'nameloc'))
                TOPO.nodes{i}.nameloc(3) = text(TOPO.nodes{i}.nameloc(1),...
                                TOPO.nodes{i}.nameloc(2),TOPO.nodes{i}.name);
        end
end

% yes, this draws the same link twice.  fix it if it matters -dam 11/21

TOPO.linkarray = [];
for i = 1:length(TOPO.links)
        TOPO.links(i).handle = drawlink(TOPO,TOPO.links(i));
        TOPO.linkarray = [TOPO.linkarray ; ...
                [ TOPO.links(i).src TOPO.links(i).dst TOPO.links(i).bw]];
end

assignin('caller',inputname(1),TOPO);
function ex(t)

t.nodes
function labelnames(TOPO)
% function labelnames(TOPO)
%   make it easy to label the nodes

for i = 1:length(TOPO.nodes)
        fprintf('Place label for node %d "%s"\n',i,char(TOPO.nodes{i}.name));

```

```
origcolor = get(TOPO.nodes{i}.mark_handle,'color');
set(TOPO.nodes{i}.mark_handle,'color',[1 0 0]);

if (isfield(TOPO.nodes{i},'nameloc'))
    good_x = TOPO.nodes{i}.nameloc(1);
    good_y = TOPO.nodes{i}.nameloc(2);
end
th = [];
while (1)
    fprintf('Button 1 to (re)place text, Button 3 to accept\n');
    [x,y,button] = ginput(1);
    if (3 == button) break; end
    if (~isempty(th)) delete(th); end
    th = text(x,y,TOPO.nodes{i}.name);
    good_x = x; good_y = y;
end
TOPO.nodes{i}.nameloc = [good_x, good_y, th];
set(TOPO.nodes{i}.mark_handle,'color',origcolor);
end

assignin('caller',inputname(1),TOPO);function names(TOPO)
% NAMES the list of names of the nodes in the topo

fprintf('Node\t\tName\n');
for i = 1:size(TOPO.names,1)
    fprintf('%d\t\t%s\n',i,TOPO.names{i});
end
function [node] = nodes(TOPO)
% function [node] = nodes(TOPO)
%   returns a cell array describing nodes in the TOPO

node = TOPO.nodes;
function [TOPO] = topo(TOPO)
% [TOPO] = topo(TOPO)
%% if input TOPO is 'init', create a new topology
%
%       newtopo = topo('init');
%
%  else add new nodes to TOPO
%
% nodes is a array of structs, one per node
% link is a array of structs, one per link
%       a link is a unidirectional item, so there are probably twice
%       as many links as you'd expect.
```

```
if (nargin < 1)
        error('topo(TOPO) or topo("init") - not enough args');
end

if (ischar(TOPO) & TOPO == 'init')
        clear TOPO

        TOPO.nodes = [];
        TOPO.links = [];

        TOPO.capacity = [];     % now computed as needed
        TOPO.locs = [];         % internal cache
        TOPO.linkarray = [];    % internal cache

        f = figure;
        axis([0 75 0 50 ]);
        TOPO.axis = axis;
        TOPO.cur_fig = f;
        axis equal
        axis manual
        box on
        hold
else
        figure(TOPO.cur_fig);
end


nodecount = length(TOPO.nodes);

while (1)
        clear nodeinfo;
        fprintf(1,'\n\nHit Button 3 to stop\n\n');
        [x y but] = ginput(1);
        if (but == 3) break; end
        x = floor(x); y = floor(y);
        nm = plot(x,y,'ob');
        name = input('Enter name > ','s');

        nodeinfo.loc = [ x y];
        nodeinfo.mark_handle = nm;
        nodeinfo.name = cellstr(name);
        nodecount = nodecount + 1;
        TOPO.nodes{nodecount} = nodeinfo;
end
```

```
if ('topo' ~= class(TOPO))
        TOPO = class(TOPO,'topo');
end

if (nargout == 0)
        assignin('caller',inputname(1),TOPO);
end
function lh = drawlink(TOPO, link)
% assumes TOPO.linkarray is already valid, and draws the position of
%  link line based on the number of links already present in linkarray

c_src = 1;
c_dst = 2;
c_bw = 3;

i = link.src;
j = link.dst;

x1 = TOPO.nodes{i}.loc(1);
y1 = TOPO.nodes{i}.loc(2);
x2 = TOPO.nodes{j}.loc(1);
y2 = TOPO.nodes{j}.loc(2);


if (isempty(TOPO.linkarray))
        num_links = 0;
else
        num_links = sum(TOPO.linkarray(:,c_src) == i & TOPO.linkarray(:,c_dst) == j);
end

pattern = [ 0 1 -1 2 -2 3 -3] * .3;

if (abs(x1 - x2) > abs(y1 - y2))
        delta_x = 0;
        delta_y = pattern(num_links + 1);
else
        delta_x = pattern(num_links + 1);
        delta_y = 0;
end

lh = line([x1 x2] + delta_x, [y1 y2] + delta_y, 'color', 'black');
function update(TOPO)
```

```
clear TOPO.locs;
for i = 1:length(TOPO.nodes)
        TOPO.locs(i,:) = TOPO.nodes{i}.loc
end

clear TOPO.linkarray;
for i = 1:length(TOPO.links)
        TOPO.linkarray = [TOPO.linkarray ; ...
                [ TOPO.links(i).src TOPO.links(i).dst TOPO.links(i).bw]];
end

% these are here to be cut and pasted into other functions as needed
%  there doesn't seem to be a good way to pass them around in another fashion
%  (using assigning('caller'...) to force their definition sounds like asking
%   for trouble 'cause you'll overwrite another definition of them...)
c_src = 1;
c_dst = 2;
c_bw = 3;

assignin('caller',inputname(1),TOPO);
```